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High-Field and Thermal Transport in Graphene

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5.1 Introduction

The rise of interest in two-dimensional (2D) materials started with graphene (Geim and Novoselov, 2007), a one-atomic layer of carbon atoms arranged into a honeycomb lattice with an interatomic distance of 1.42 \AA , as shown in **Figure 5.1**. Carbon atoms in graphene are bonded through orbitals with sp^2 hybridisation, which leads to a strong bond and excellent mechanical strength. A single atomic layer (monolayer) of graphene is nearly 98% transparent to visible light, enabling the design of graphene-based transparent electrodes (Kim et al., 2009a). Graphene is flexible and shows great electrical characteristics under mechanical strain, which also enables the design of flexible electronic applications (Lee et al., 2008). In addition to outstanding mechanical, electrical and thermal properties, which we will cover later, graphene-based technology benefits from the abundance, nontoxicity and biocompatibility of carbon.

There are several ways to obtain graphene. The simplest method is mechanical exfoliation from graphite using adhesive (e.g. ScotchTM) tape, which led to the discovery of the field-effect properties of graphene in 2004 (Novoselov et al., 2004) and eventually to the Nobel Prize in Physics in 2010 (Geim, 2011, Novoselov, 2011). Although this method produces small samples (e.g. $\sim 10 \text{ \mu m}$) of excellent quality, its industrial applications are limited due to lack of process scalability. Graphene can also be grown by epitaxy on SiC substrate (Kedzierski et al., 2008). Some difficulties associated with this process include the relatively expensive and small size of SiC wafers, plus the difficulty in obtaining undoped graphene samples by this method. The most common way to obtain graphene these days is the chemical vapour deposition (CVD) process using a catalyst such as Cu (Li et al., 2009). After growth, the graphene is coated with a polymer such as poly(methyl methacrylate) or poly(bisphenol A carbonate) and transferred to the substrate of interest (Wood et al., 2015). A challenge of the CVD process is that due to somewhat random character of the growth, it leads to polycrystalline graphene layers with grain boundaries and line defects (Huang et al., 2011).

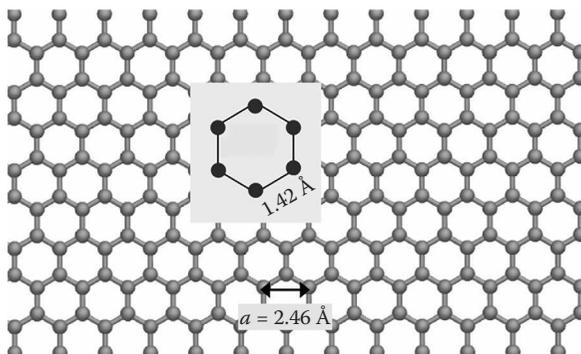


FIGURE 5.1 Structure of graphene showing hexagonally arranged carbon atoms with spacing 1.42 \AA and lattice constant $a = 2.46 \text{ \AA}$.

As mentioned earlier, graphene has outstanding electrical and thermal properties stemming from its electron and phonon energy dispersions, shown in **Figure 5.2**. Unlike most semiconductors or metals, graphene has a linear electron energy band structure near the Fermi level, that is, $E = \hbar v_F |\mathbf{k}|$, where \hbar is the reduced Planck constant and $v_F \approx 10^6$ m/s is the Fermi velocity of charge carriers, that is, their ballistic velocity between collisions (Castro Neto et al., 2009). The linear dispersion also indicates that the density of states (DOS) for electrons in graphene is linearly proportional to their energy (Fang et al., 2007):

$$\text{DOS}(E) = \frac{2}{\pi(\hbar v_F)^2} |E| \tag{5.1}$$

where factors of 2 are included for valley degeneracy (K and K') and spin degeneracy, respectively.

As shown in **Figure 5.2a**, graphene has a zero band gap, with the point where conduction band meets valence band called the Dirac point. There are two equivalent zero-gap points at the K and K' locations in the Brillouin zone (BZ) of graphene. The minimum carrier density is observed when the Fermi level is at the Dirac point, and in theory is limited only by the thermally generated carrier density in thermal equilibrium (Fang et al., 2007):

$$n = p = n_i = \frac{\pi}{6} \left(\frac{k_B T}{\hbar v_F} \right)^2, \tag{5.2}$$

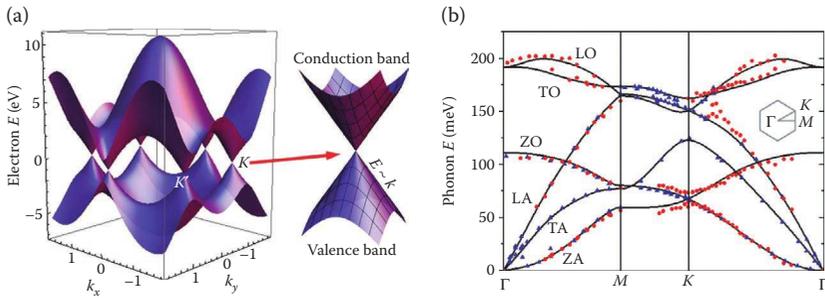


FIGURE 5.2 (a) Graphene electron energy band structure with zoom-in to show linear dispersion near the K (or K') point of the BZ. The energy bands deviate from linear behaviour at energies greater than ~ 1 eV (Serov et al., 2014). (Biro, L. P., Nemes-Incze, P. and Lambin, P. 2012. Graphene: Nanoscale processing and recent applications. *Nanoscale*, 4, 1824–1839. Reproduced by permission of The Royal Society of Chemistry.) (b) Phonon energy dispersion along high-symmetry lines for monolayer graphene obtained from *ab initio* calculations, where red circles (Yanagisawa et al., 2005) and blue triangles (Mohr et al., 2007) are experimental data plotted for comparison. The inset shows the graphene BZ.

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where k_B is the Boltzmann constant and T is the temperature. However, in reality, various ionised impurities can induce local changes in the Dirac point, so-called ‘potential energy puddles’, which also increase the minimum carrier density (Zhang et al., 2009, Li et al., 2011a).

The fact that we cannot effectively decrease the carrier density means that graphene field-effect transistors (FETs) are difficult to switch off, making it challenging to utilise graphene for applications in digital electronics. Although a band gap can be introduced by quantum confinement, that is, patterning graphene into nanoribbons (GNRs), the GNR width corresponding to a reasonable band gap of ~ 0.5 eV is around just a few nanometers (Son et al., 2006, Han et al., 2007, Li et al., 2008, Huang et al., 2009), making the edges and associated edge roughness a significant part of the device. In reality, the mobility in narrow GNRs is typically lower than in pristine graphene even for 10–20-nm-wide devices (Jiao et al., 2009, Behnam et al., 2012). High mobility and good current density in large-scale graphene can be utilised in analogue applications and interconnects (Lin et al., 2010, Behnam et al., 2012, Wu et al., 2012), where off-state leakage is less important, while high on-current and transconductance (gain) are crucial. These applications as well as potential high-performance digital electronics require careful thermal management, where graphene can also play a role due to high thermal conductivity (k) (Balandin, 2011, Pop et al., 2012, Xu et al., 2014b).

The thermal properties of graphene can be better understood by inspecting the phonon dispersion, as shown in **Figure 5.2b**. Phonons, that is, the quantised lattice vibrations of single-layer graphene (SLG) have six branches corresponding to two atoms in the elementary cell: three acoustic modes (transverse TA, longitudinal LA and flexural ZA) and three optical modes (transverse TO, longitudinal LO and flexural ZO). Transverse and longitudinal acoustic modes have high sound velocity $v_{LA} \approx 21$ km/s and $v_{TA} \approx 14$ km/s (Pop et al., 2012), which leads to a strong contribution to thermal conductivity. Flexural ZA and ZO modes correspond to out-of-plane vibrations. Unlike linear LA and TA modes, ZA has a quadratic dependence of frequency ω on wave vector q : $\omega \approx \alpha q^2$, which leads to the high DOS and big contribution to the thermal conductivity for *suspended* samples (Lindsay et al., 2010), which could exceed 2000 W/m/K at room temperature (Balandin, 2011, Pop et al., 2012, Xu et al., 2014b). For samples on a substrate (e.g. SiO₂), ZA modes are suppressed by the interaction with the substrate (Seol et al., 2010, Ong and Pop, 2011), which leads to lower but still great thermal conductivity of supported samples $k \approx 600$ W/m/K (Seol et al., 2010). The thermal transport in graphene will be discussed in detail in **Section 5.3**.

Now, we first return to the electrical properties of graphene. Suspended samples with exfoliated graphene allow probing of intrinsic electrical properties and exhibit charge carrier mobility as high as $\sim 100,000$ cm²/V/s albeit at low temperature (~ 5 K) and low carrier density $n \sim 10^{10}$ – 10^{11} cm⁻² (Bolotin et al., 2008). Such a high low-field mobility in suspended graphene can be explained by weak electron–phonon coupling, especially at lower carrier densities due to relatively high energy of optical phonons ($\hbar\omega_{OP} \approx 200$ meV) and intervalley acoustic phonons ($\hbar\omega_{AC,i} \approx 140$ meV) (Balandin, 2011,

Pop et al., 2012). As the energy of these phonons is much higher than $k_B T \approx 26$ meV at room temperature, the number of carriers which can *emit* these phonons is very low for equilibrium Fermi–Dirac distribution. On the other hand, the probability to *absorb* a high-energy phonon is limited by the nature of the Bose–Einstein distribution for phonons. The reasoning provided here is valid only in near-equilibrium conditions (low field), as it is much easier to emit optical phonons for non-equilibrium high-energy so-called ‘hot’ carriers (Serov et al., 2014).

Although suspended graphene devices exhibit outstanding electrical properties, their utilisation for realistic electronics is very limited. First, the manufacturing of suspended devices is a challenging process with low throughput (Bolotin et al., 2008, Dorgan et al., 2013). Second, it is difficult to modulate charge carrier density in suspended samples because of very weak capacitive coupling between graphene and the gate through the air or vacuum gap. Therefore, in order to make devices and circuits, graphene is most commonly placed on substrates compatible with conventional CMOS (complementary metal–oxide–semiconductor) processing, for example, Si/SiO₂, Al₂O₃ or HfO₂. However, when graphene is placed on a substrate, its electrical characteristics degrade quite significantly, with the low-field mobility typically less than 10,000 cm²/V/s. Such steep degradation of the low-field mobility is related to various substrate-induced scattering mechanisms such as ionised impurity scattering and surface phonon scattering (Adam et al., 2009, Zhu et al., 2009, Perebeinos and Avouris, 2010, Ong and Fischetti, 2012c, Serov et al., 2014).

As graphene could be targeted towards interconnects and analogue applications, the understanding of electrical transport at high electric fields can be beneficial for device analysis and optimisation. High-field transport in graphene has been studied both theoretically and experimentally. Experimental analysis is usually performed on a four-point structure or in multi-finger Hall configuration to exclude the effect of the contact resistance (Barreiro et al., 2009, DaSilva et al., 2010, Dorgan et al., 2010). It is usually observed that the current in graphene tends to saturate at higher electric field but does not reach ‘true’ saturation with output conductance $g_d = dI_d/dV_d$ nearly zero (Barreiro et al., 2009, DaSilva et al., 2010, Dorgan et al., 2010). However, despite the lack of current saturation, it is possible to observe velocity saturation, albeit accompanied by the rising device temperature due to self-heating (Dorgan et al., 2010).

From the theoretical side, the velocity saturation in graphene is not an easy problem to solve, mostly due to the complicated nature of interaction of charge carriers in graphene with the substrate. The first theoretical studies of velocity saturation in graphene focussed on intrinsic graphene behaviour, therefore, mostly neglecting the substrate effect (Akturk and Goldsman, 2008, Shishir and Ferry, 2009). The tool of choice in this case is usually the Monte-Carlo method in momentum space, which naturally provides a simulation scheme for multiple scattering mechanisms (Jacoboni and Reggiani, 1983). The hydrodynamic model can also be used for modelling of high-field effects and has some advantages (Bistritzer and MacDonald, 2009, Svintsov et al., 2012, Serov et al., 2014).

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Earlier theoretical studies on intrinsic graphene exhibit quite different results for velocity saturation: for example, one study demonstrated carrier-density-dependent saturation velocity v_{sat} in the range between $0.3v_{\text{F}}$ and $0.45v_{\text{F}}$ using the ensemble Monte-Carlo method (Shishir and Ferry, 2009). Another study showed almost no carrier-density dependence in velocity saturation with much lower bound for v_{sat} around $0.1v_{\text{F}}$ (Bistritzer and MacDonald, 2009). The main difference between the two models lies in values for deformation potentials for acoustic and optical phonons employed.

Later investigations (Li et al., 2010, 2011b, Perebeinos and Avouris, 2010), which incorporated the role of the substrate, pointed to the importance of interfacial substrate phonon modes and self-heating. However, the treatment of the substrate phonons was first performed with relatively simplistic models including no screening or static screening. A Monte-Carlo study involving substrate phonons (with static screening, but no substrate impurities) showed the velocity saturation between $0.4v_{\text{F}}$ and $0.6v_{\text{F}}$ (Li et al., 2010). The same group performed a similar study with self-heating taken into account and found carrier-density-dependent velocity saturation with v_{sat} ranging between $0.15v_{\text{F}}$ and $0.5v_{\text{F}}$ (Li et al., 2011b). Similar results were shown using Monte-Carlo methods by another group, where substrate phonons were treated without screening yielding very high values for v_{sat} between $0.4v_{\text{F}}$ and $0.8v_{\text{F}}$ depending on the substrate material (between $0.4v_{\text{F}}$ and $0.5v_{\text{F}}$ for intrinsic graphene) (Perebeinos and Avouris, 2010). However, a recent detailed pseudo-potential-based Monte-Carlo study (with dynamic screening theory but without self-heating) pointed to lower numbers about $0.2v_{\text{F}}$ to $0.3v_{\text{F}}$ at room temperature (Fischetti et al., 2013). A more comprehensive study (Serov et al., 2014) using a hydrodynamic model considered self-heating and thermal coupling to the substrate, scattering with ionised impurities, graphene phonons, dynamically screened interfacial plasmon–phonon (IPP) modes and various substrates. It found that the high-field behaviour is determined by scattering with IPP modes and a small contribution of graphene phonons, and the drift velocity was benchmarked with available experimental data (Dorgan et al., 2010).

High-field effects in graphene are important not only in static (DC) regimes, but can also lead to a variety of interesting physical transient effects, especially at higher frequencies (Sekwao and Leburton, 2013). These effects render interesting features of electron–electron and electron–phonon interactions in zero band gap graphene. Up to this point, we have been discussing the characterisation of material properties of graphene usually performed experimentally in specialised test structures or in simulation with complicated methods such as the Monte Carlo or hydrodynamic model. A simpler characterisation usually involves a lumped compact model and basic extraction of transport coefficients such as mobility and contact resistance on a simple three- or four-terminal metal–oxide–semiconductor field-effect transistor (MOSFET) device. In order to bring together material properties and real device geometry, other methods such as the drift-diffusion model can be used to assist with device analysis. For instance, current saturation in graphene devices is an important topic because it is related to the analogue transistor gain, with better saturation resulting in higher gain ($=g_{\text{m}}/g_{\text{d}}$, where $g_{\text{m}} = \partial I_{\text{D}}/\partial V_{\text{GS}}$ is the

transconductance and g_d is the output conductance defined earlier). However, current saturation is not only caused by velocity saturation but also can be assisted electrostatically similar to the pinch-off effect in silicon MOSFETs, which can be captured by the Poisson equation in the drift-diffusion scheme. Other physical effects occurring alongside current saturation are band-to-band carrier generation and impact ionisation (Winzer et al., 2010, Girdhar and Leburton, 2011, Pirro et al., 2012). Despite the drift-diffusion method proving its merit for bulk semiconductors, relatively fewer efforts had assessed the applicability of drift-diffusion techniques to graphene (Ancona, 2010, Bae et al., 2011, Jimenez, 2011, Islam et al., 2013). In the next section, we will mainly discuss high-field electronic transport in graphene.

5.2 High-Field Electronic Transport in Graphene

5.2.1 Practical Device Operation and High-Field Transport

Understanding high-field electronic transport in a material like graphene is not only important from a scientific point of view, but is also essential for achieving practical applications. This can be further understood by comparing the long-channel model versus the short-channel model for a typical n-channel FETs. The basic long-channel NMOSFET equation for calculating drain current (I_D) is given by (Muller et al., 2003)

$$I_D = \mu C_{ox} \frac{W}{L} \left[\left(V_{GS} - V_T - \frac{1}{2} V_{DS} \right) V_{DS} \right], \quad (5.3)$$

where μ is the carrier mobility, L and W are the channel length and width, respectively, C_{ox} is the gate oxide capacitance per unit area, V_{GS} is the gate voltage, V_T is the threshold voltage and V_{DS} is the drain voltage, all with reference to the grounded source terminal. Using the long-channel model, when $V_{DS} > V_{GS} - V_T$ the inversion layer at the drain is effectively ‘pinched-off’ as shown in **Figure 5.3**, and I_D no longer rises with an increase in V_D . This occurs when the gate-to-drain voltage is smaller than the threshold voltage ($V_{GD} = V_{GS} - V_{DS} < V_T$) and can no longer support sufficient inversion charge at the drain end of the channel. The classical long-channel saturation current (I_{Dsat}) is defined by the drain voltage at the pinch-off point ($V_{DS} = V_{GS} - V_T$) and given by

$$I_{Dsat} = \mu C_{ox} \frac{W}{2L} (V_{GS} - V_T)^2, \quad (5.4)$$

where the classical I_{Dsat} increases quadratically with the gate voltage overdrive ($V_{GS} - V_T$) and is inversely proportional to L .

The long-channel analysis, which assumes carrier mobility independent of lateral field, is no longer applicable at higher electric fields present in short-channel transistors. These higher fields result in the drift velocity (v_d) of carriers in short-channel devices approaching a limiting value known as the saturation velocity (v_{sat}). This leads to current saturation occurring in

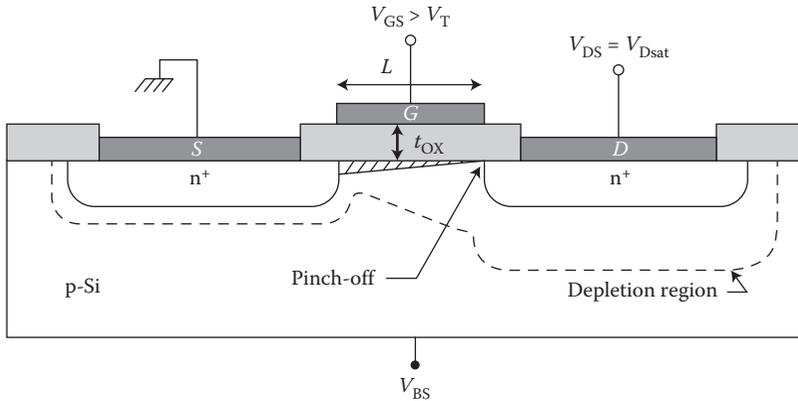


FIGURE 5.3 Schematic of a typical long-channel n-type MOSFET, shown in this case at the onset of saturation such that the pinch-off point is at the drain side of the channel. (Adapted from Taur, Y. and Ning, T. H. 2009. *Fundamentals of Modern VLSI Devices*. Cambridge University Press, New York. Copyright 2009.)

a short-channel transistor at much lower voltages than one would predict if using the long-channel model (Taur et al., 1993, Taur and Ning, 2009). Consequently, for short-channel MOSFETs, the saturation current is given by

$$I_{Dsat} \approx v_{sat} WC_{ox} (V_{GS} - V_T - V_{DSat}), \quad (5.5)$$

if one assumes velocity saturation along the entire channel length, where V_{DSat} is the drain voltage at the onset of current saturation. For shorter and shorter gate lengths ($L \rightarrow 0$), we can estimate the maximum drain current as

$$I_{Dmax} = v_{sat} WC_{ox} (V_{GS} - V_T), \quad (5.6)$$

where I_{Dmax} increases linearly, not quadratically, with overdrive voltage ($V_{GS} - V_T$) and the term $C_{ox}(V_G - V_T)$ is an approximation of the 2D carrier density (n) in the channel. **Figure 5.4** shows a comparison of the high-field behaviour for long- and short-channel devices discussed here, and further emphasises that with increased scaling and higher electric fields in modern transistors, improved understanding of high-field transport (i.e. the energy dissipation mechanisms that determine v_{sat} for a given material) is critical for enhancing practical device operation. The velocity saturation in a typical semiconductor with *parabolic* energy bands (like Si) can be simply estimated as (Lundstrom, 2000)

$$v_{sat} \approx \left(\frac{\hbar\omega_{OP}}{m^*} \right)^{1/2}, \quad (5.7)$$

where $\hbar\omega_{OP}$ is the optical phonon energy (responsible for the majority of inelastic scattering) in the material and m^* is the conductivity effective mass.

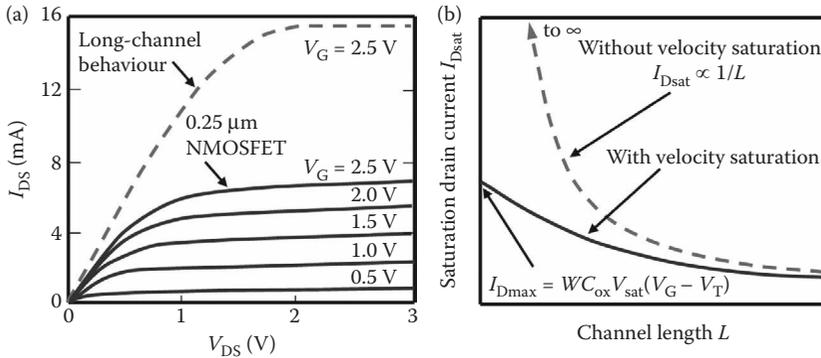


FIGURE 5.4 (a) Current–voltage characteristics for a Si NMOSFET with $L = 0.25 \mu\text{m}$ and $W = 9.5 \mu\text{m}$. The solid lines are experimental curves, whereas the dashed line is the long-channel approximation with velocity saturation effects ignored. (Adapted from Taur, Y. et al. 1993. *Solid-State Electron.*, 36, 1085–1087.) (b) Model predictions for MOSFET saturation current versus channel length without velocity saturation (dashed) and with velocity saturation (solid). (Adapted from Muller, R. S. et al. 2003. *Device Electronics for Integrated Circuits*. John Wiley & Sons, New York.)

$v_{\text{sat}} \approx 10^7 \text{ cm/s}$ in Si for both electrons and holes (Jacoboni et al., 1977). However, as we will see, this expression does not hold for graphene, where the energy bands near the Fermi level have a *linear* dispersion relationship.

Detailed knowledge of the coupling of high-field transport with self-heating is also necessary when discussing practical device operation, since the ability to effectively remove heat from integrated circuits is a limiting factor for future scaling. At high fields, the charge carriers (e.g. electrons in conduction band) accelerate and gain energy, or ‘heat up’. Mechanisms that may limit electron transport include electron scattering with other electrons, phonons, interfaces, defects and impurities. These scattering events not only determine v_{sat} , but also when electrons scatter with phonons, electrons can lose energy to the lattice and effectively raise the temperature of the lattice (i.e. Joule heating or self-heating) (Pop et al., 2005, Pop and Goodson, 2006, Pop et al., 2006b). Consequently, it is important to account for self-heating effects when investigating high-field transport, as the electronic properties of a material may vary drastically with temperature. For example, the saturation velocity in Si shows a slight decrease with rising temperature due to an increase in phonon scattering (Jacoboni et al., 1977).

5.2.2 High-Field Transport in Graphene

For high-field transport in graphene, our discussion here is primarily concerned with monolayer graphene under steady-state transport. First, we focus on simulation results for ideal graphene and then include analysis of substrate effects and experimental data.

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A detailed review of the current theoretical understanding of electron transport in graphene has recently been presented by Fischetti et al. (2013). Here, we summarise some of the key points from their study, as well as other theoretical works, as they pertain to our discussion of high-field transport. We initially give attention to phonon-limited transport in ideal graphene, as shown in **Figure 5.5**. We point out that the electron drift velocity appears to peak at $\sim 2 \times 10^7$ cm/s at 1 V/ μm field for $n = 10^{13}$ cm $^{-2}$ at 300 K. The onset of negative differential velocity (NDV) at 0.3–0.5 V/ μm for lower carrier densities is an intriguing prediction, and here it is attributed to electrons gaining enough energy at high fields to populate the flatter regions of the BZ (**Figure 5.2a**), causing a decrease of the drift velocity. The appearance of NDV has been presented in previous simulations as well (Akturk and Goldsman, 2008, Shishir and Ferry, 2009, Shishir et al., 2009).

Using Monte-Carlo simulations, Akturk and Goldsman (2008) predicted peak drift velocities for intrinsic graphene as high as 4.6×10^7 cm/s and slight NDV for fields above ~ 10 V/ μm . Shishir and Ferry (2009) estimate similar peak velocities and NDV for $n \leq 2 \times 10^{12}$ cm $^{-2}$ at fields above ~ 0.5 V/ μm . Chauhan and Guo (2009) show carrier velocity as a function of electric field up to 1 V/ μm with v_{sat} near 4×10^7 cm/s, but without NDV ostensibly due to their use of a simple linear dispersion. However, the carrier density was fixed at 5.29×10^{12} cm $^{-2}$ in their simulations so it is uncertain if NDV would have been observed at lower densities. The calculated v_d versus electric field for these works is summarised in **Figure 5.6**. The variation among different theoretical works for transport in ideal graphene may, at least in part, be associated

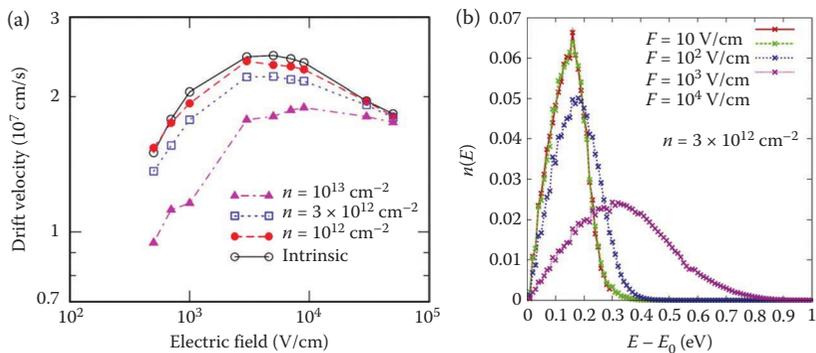


FIGURE 5.5 (a) Drift velocity versus electric field in graphene at 300 K calculated using the Monte-Carlo method (Fischetti et al., 2013), and considering only phonon-limited electron transport, that is, electron–electron scattering, substrate effects and self-heating are ignored. The various curves are distinguished by the electron density (n). (b) Corresponding electron energy distribution function calculated for various values of the electric field (F) for the case of $n = 3 \times 10^{12}$ cm $^{-2}$. (Adapted from Fischetti, M. V. et al., Pseudopotential-based studies of electron transport in graphene and graphene nanoribbons. *J. Phys. Condens. Matter*, 25, 473202. Copyright 2013, Institute of Physics.)

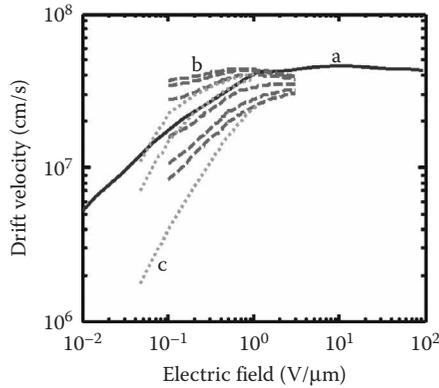


FIGURE 5.6 Calculated drift velocity versus electric field from Monte-Carlo simulations from (solid) Akturk and Goldsman (2008) (a), (dashed) Shishir and Ferry (2009) (b) and (dotted) Chauhan and Guo (2009) (c). The solid line corresponds to intrinsic graphene. The dashed lines vary in carrier density from 5×10^{11} to 10^{13} cm^{-2} from top to bottom. The multiple dotted lines have impurity densities of $n_{\text{imp}} = 0, 10^{11} \text{ cm}^{-2}$ and 10^{12} cm^{-2} from top to bottom.

with the different choices made for deformation potentials, band structures and phonon dispersions. Therefore, drawing qualitative, rather than quantitative, conclusions may be more appropriate from these simulation studies. For example, a clear observation in Fischetti et al. (2013) and Shishir et al. (2009) is the decrease in high-field drift velocity with increasing carrier density, which is an interesting phenomenon considering typical non-degenerate semiconductors like Si have a constant v_{sat} (e.g. $\sim 10^7 \text{ cm/s}$ for Si at 300 K) (Jacoboni et al., 1977). Graphene has no band gap, and thus is a degenerate semiconductor where the dependence of saturation velocity on carrier density is due to the degeneracy of carriers and the Pauli exclusion principle (Fang et al., 2011).

Continuing the discussion of the carrier-density-dependent electron transport in graphene, we note that simulations by Ferry (2012) used an impurity density that increased with carrier density, indicating that this increasing impurity density was the only way to match the experimental data of Dorgan et al. (2010) and Kim et al. (2012). It is plausible that a change in impurity density may occur during measurements due to the application of a high gate field and subsequent motion of impurities within the oxide. Another explanation is that a more dynamic form of screening, as proposed by Ong and Fischetti (2012c), is necessary to properly understand the dependence of transport on carrier density. For future analysis of experimental work, we note that a constant impurity density (independent of gate voltage) is assumed.

Returning to the previously mentioned high-field NDV in graphene shown in several theoretical studies (Akturk and Goldsman, 2008, Shishir and Ferry, 2009, Shishir et al., 2009, Fischetti et al., 2013), Fang et al. (2011) suggest that the inclusion of electron–electron (e – e) scattering actually removes the NDV effect. Because high-energy electrons exchange their momentum and energy

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with low-energy electrons, e - e scattering weakens the backscattering effect that would lead to NDV (Fang et al., 2011). Another effect not yet discussed is carrier multiplication due to interband tunnelling and e - e scattering (Winzer et al., 2010, Girdhar and Leburton, 2011, Pirro et al., 2012). If the Fermi level is near the Dirac point, we could expect Zener tunnelling and/or impact ionisation to generate electrons and holes, especially at high fields, and increase the carrier concentration. Experimental studies have shown that it is very difficult to obtain saturation of high-field current in graphene transistors (Meric et al., 2008, Barreiro et al., 2009, DaSilva et al., 2010, Dorgan et al., 2010, Meric et al., 2011), a characteristic credited to the lack of a band gap in graphene, which facilitates ambipolar transport and the easy transition from electron-dominated to hole-dominated transport (or vice versa) during high-field operation.

We now turn to substrate effects, a necessary discussion in light of the fact that a majority of the experimental work on graphene has been performed with graphene on solid insulating substrates (e.g. SiO₂/Si). An additional scattering process that limits electrical transport in supported graphene is scattering with charged impurities (Chen et al., 2008) and 'remote' substrate phonons (Serov et al., 2014). Substrate impurities that remain after the fabrication of graphene transistors (Martin et al., 2008, Deshpande et al., 2009, Zhang et al., 2009) play a significant role in limiting the low-field mobility of graphene transistors (Adam et al., 2007), but do not significantly affect high-field transport (Perebeinos and Avouris, 2010, Meric et al., 2011). In addition, we expect that if a graphene transistor is used in the future for nanoscale electronics, then it will most likely be a top- or multi-gated transistor with thin high- k insulator as the gate dielectric (Kim et al., 2009b, Zou et al., 2010). Detailed models have been provided for analysing the effect of charged impurity scattering and its dependence on the surrounding dielectric environment (Chen et al., 2009a, Ponomarenko et al. 2009, Ong and Fischetti, 2012a, 2013b), but as we are primarily concerned with high-field transport here, we will move on to a more relevant scattering process.

For insulators like SiO₂ and HfO₂, there are bulk dipoles associated with the ionicity of the metal-oxide bonds. These dipoles generate fringing fields on the substrate surface such that the frequencies of the dipoles are typically determined by the bulk LO phonons of the insulator. Electrons in close proximity to the substrate surface may interact with these surface optical (SO) phonons via a process commonly referred to as remote-phonon scattering. For Si inversion layers, remote-phonon scattering has been investigated (Hess and Vogl, 1979, Moore and Ferry, 1980), where it was found to have a small effect on the drift velocity in the regime just beyond Ohmic transport, but it was not strong enough to affect the saturation velocity (Leburton and Dorda, 1981), which is determined by the bulk Si optical phonons. In supported graphene, it is reasonable to consider electrons interacting strongly with SO phonons, considering electrons are essentially confined to the graphene sheet and the van der Waals gap between the graphene and substrate is small, ~ 0.3 nm (Ishigami et al., 2007). Furthermore, recent work shows that graphene may

even emit longitudinal out-of-plane acoustic phonons into the substrate, representing an energy dissipation mechanism in the vertical direction (Chen et al., 2014).

When discussing remote-phonon scattering in graphene, Ong and Fischetti (2012b,c, 2013a) indicated the importance of considering dynamic screening and the charge density response of graphene due to the electric field created by SO phonons. **Figure 5.7** shows the remote-phonon-limited mobility (μ_{RP}) in graphene as a function of carrier density for various supporting substrates. The mobility is calculated by accounting for the hybrid IPP modes formed from the hybridisation of the SO phonons with graphene plasmons (Ong and Fischetti, 2012c). We see from the plot that μ_{RP} is saturating and weakly dependent on n at high carrier densities since most of the remote phonons are dynamically screened. The observed behaviour agrees with the findings of Zou et al. (2010), who extract μ_{RP} showing a slight increase with carrier density for a graphene transistor with HfO_2 as the top-gate dielectric.

The experimental works of Meric et al. (2008, 2011) suggest that current saturation in a graphene transistor may be observed due to remote-phonon scattering, or more specifically, scattering with the low-energy SO phonon of SiO_2 at $\hbar\omega_{OP} \approx 55$ meV (Fischetti et al., 2001). We use the term ‘low-energy’ here for comparison to the graphene (zone-edge) optical phonon with energy $\hbar\omega_{OP} \approx 160$ meV (see **Figure 5.2b**) (Borysenko et al., 2010). Furthermore, Barreiro et al. (2009) also suggested that the calculated current (from the analytic model shown in **Figure 5.9a**) using an average phonon energy of 149 meV overestimates the experimentally observed current in the

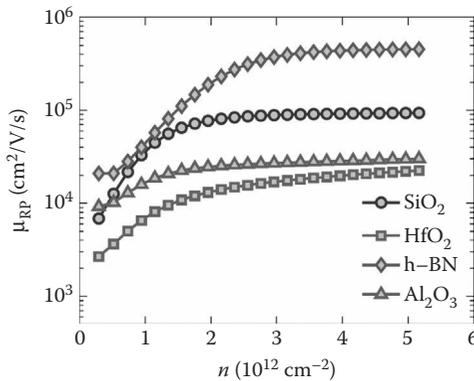


FIGURE 5.7 Remote-phonon-limited mobility (μ_{RP}) versus electron density (n) calculated using theory accounting for hybrid IPP modes (Ong and Fischetti, 2012b,c). Graphene is supported by various substrates: SiO_2 (circles), HfO_2 (squares), h -BN (diamonds) and Al_2O_3 (triangles), where degradation in mobility with increasing substrate dielectric constant is evident. (Adapted from Ong, Z.-Y. and Fischetti, M. V. 2012b. Erratum: Theory of interfacial plasmon-phonon scattering in supported graphene. *Phys. Rev. B*, 86, 199904. Copyright 2012 by the American Physical Society.)

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high-field limit. Unfortunately, these works do not account for self-heating effects in their analysis, which we know is evident in graphene transistors at high currents and high fields (Chae et al., 2009, Freitag et al. 2009, Bae et al., 2010, 2011, Berciaud et al., 2010) and appears necessary to explain high-field transport in graphene (DaSilva et al., 2010, Perebeinos and Avouris, 2010, Li et al., 2011b, Islam et al., 2013).

Figure 5.8 shows the extracted drift velocity as a function of electric field from experimental I - V data of multiple studies for graphene-on-SiO₂ devices (Barreiro et al., 2009, DaSilva et al., 2010, Dorgan et al., 2010, Meric et al., 2011). Direct comparison of these curves is difficult as they correspond to different values of carrier density and temperature, as well as different device structures. Nevertheless, we are able to highlight some key features of high-field transport in graphene. Saturation velocity in graphene, even at high carrier densities $>10^{13}$ cm⁻², appears to be larger than 10^7 cm/s (i.e. larger than v_{sat} in Si at room temperature). For suspended graphene, the extracted saturation velocity from high-field measurements at high temperature (>1000 K) is between 1 and 3×10^7 cm/s (Dorgan et al., 2013). **Figure 5.8** also shows the decrease

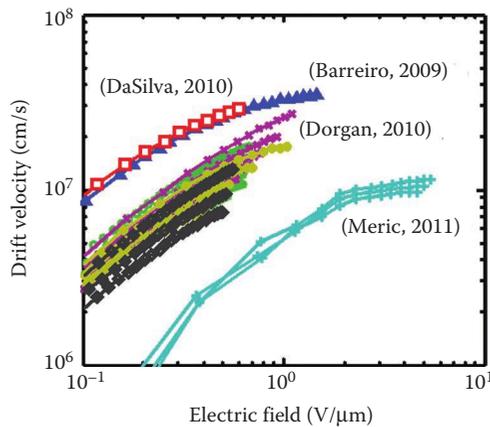


FIGURE 5.8 Experimentally extracted drift velocity versus electric field corresponding to data from Barreiro et al. (2009) for $T_0 = 300$ K at $n \approx 1.7 \times 10^{12}$ cm⁻² (blue triangles), DaSilva et al. (2010) for $T_0 = 20$ K at $n \approx 2.1 \times 10^{12}$ cm⁻² (red squares), Meric et al. (2011) for $T_0 = 300$ K at $n \approx 1.1 \times 10^{12}$ – 1.4×10^{12} cm⁻² from top to bottom (cyan crosses) and Dorgan et al. (2010) for $T_0 = 80$ K at $n \approx 1.9 \times 10^{12}$ – 5.9×10^{12} cm⁻² from top to bottom (magenta crosses), for $T_0 = 300$ K at $n \approx 2.8 \times 10^{12}$ – 6.6×10^{12} cm⁻² from top to bottom (tan stars), for $T_0 = 80$ K at $n \approx 2.9 \times 10^{12}$ – 1.23×10^{13} cm⁻² from top to bottom (green circles) and for $T_0 = 450$ K at $n \approx 2.7 \times 10^{12}$ – 7.5×10^{12} cm⁻² from top to bottom (black diamonds). Data from Meric et al. (2011) correspond to a top-gated device with $L = 130$ nm and a relatively low low-field mobility due to high-impurity scattering. Consequently, velocity saturation effects are observed at relatively higher fields than the other devices shown here, which are all larger, back-gated SiO₂-supported graphene transistors.

in high-field drift velocity with increasing carrier density, as mentioned above and shown in previous theoretical works. Similarly, the high-field drift velocity decreases with increasing temperature, which is an expected trend if we assume high-field transport is limited by emission of optical phonons.

Lastly, in **Figure 5.9a**, we summarise the practical analytic models from Dorgan et al. (2010), Freitag et al. (2009) and Fang et al. (2011). These models assume that velocity saturation in graphene is caused by a single optical phonon of energy $\hbar\omega_{OP}$. The first model (Dorgan et al., 2010), as shown in **Figure 5.9a**, approximates the high-field electron distribution with two half-disks such that positive- k_x electrons are populated to an energy $\hbar\omega_{OP}$ higher than negative- k_x moving electrons. The assumption here is that the inelastic process of emitting an OP causes the electron to instantly backscatter. The second model (Freitag et al., 2009) shown in **Figure 5.9b** assumes that for a given electron density defined by $n = k_F^2/\pi$, the high-field transport regime simply consists of electrons within a $\pm\hbar\omega_{OP}/2$ window around the Fermi energy E_F , such that $E_F = \hbar v_F k_F = \hbar v_F (\pi n)^{1/2}$. The last model (Fang et al., 2011) (**Figure 5.9c**) considers a low-energy disk (k_l) and a high-energy disk (k_h) defined by $\omega_{OP}/v_F = k_h - k_l$, such that if an electron travelling along the k_x -direction reaches the high-energy circle, then it instantly emits an OP and backscatters. This ‘streaming’ model (Fang et al., 2011) accounts for carrier degeneracy in graphene by assuming that the occupation of the low-energy circle is so

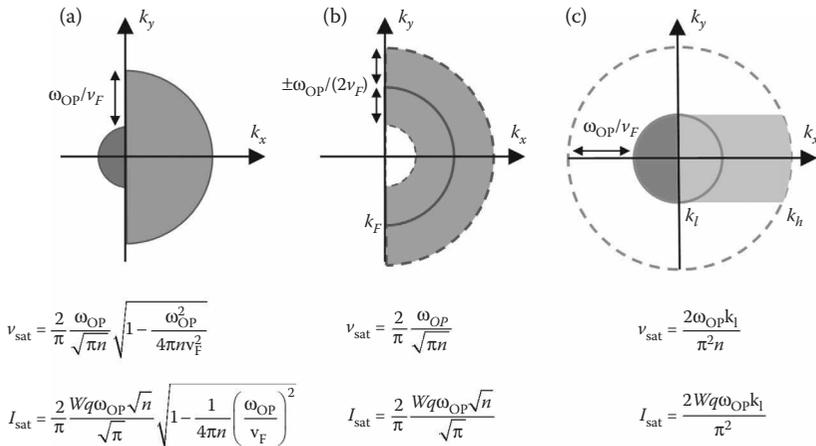


FIGURE 5.9 Simplified models for high-field electron distribution and velocity saturation in graphene. The electric field is oriented along the x-axis. The shaded regions represent the portions of k -space populated by electrons, as the high-field electron distribution is distorted from equilibrium (circular disk). Analytic models from (a) Dorgan et al. (2010) and Barreiro et al. (2009); (b) Freitag et al. (2009) and Perebeinos and Avouris (2010) and (c) Fang et al. (2011). These models assume a single optical phonon with energy $\hbar\omega_{OP}$ is responsible for velocity saturation. The equations for velocity saturation v_{sat} and current saturation I_{sat} based on each model are provided as well.

full that the Pauli exclusion principle prohibits an electron with energy less than $E_h = \hbar v_F k_h$ to emit an OP, which forces the distribution function to be squeezed and elongated along the direction of the electric field.

We emphasise that these analytic models are more suited for empirical fitting and compact modelling of transistors. It is known that even small changes in the electron distribution can significantly affect charge transport, and thus, these models most likely oversimplify the distribution of carriers during high-field operation. Nevertheless, the compact models give the correct dependence of velocity saturation on carrier density and the magnitude of the phonon responsible (assuming that a single phonon energy is dominant). For example, Dorgan et al. (2010) fit against experimental data using a dominant phonon of ~ 81 meV, which is a value between that of the SiO₂ substrate phonon and the intrinsic graphene OP, suggesting that both may be playing a role – a scenario examined in more depth by Serov et al. (2014).

5.3 Thermal Transport in Graphene

5.3.1 Intrinsic Thermal Conductivity of Graphene

We now turn to the discussion of thermal transport in graphene, with implications both for transistors and interconnects. First, we focus on the ‘intrinsic’ thermal conductivity (k) of SLG. Here, by ‘intrinsic’, we mean isolated graphene without impurities, defects, interfaces and edge scattering, so its thermal conductivity is only limited by intrinsic phonon–phonon scattering due to crystal anharmonicity (Balandin, 2011) and electron–phonon scattering. In experiments, suspended, micrometer scale graphene samples have properties close to intrinsic ones. We thus first summarise current experimental observations of k in suspended SLG.

Using the Raman thermometry technique (Balandin, 2011, Xu et al., 2014b), suspended micro-scale graphene flakes obtained by both exfoliation from graphite (Balandin et al., 2008, Ghosh et al., 2008, 2009, 2010, Faugeras et al., 2010; Lee et al., 2011) and CVD growth (Cai et al., 2010, Chen et al., 2011, 2012a,b, Vlasiouk et al., 2011) have been measured at room temperature and above. Some representative data versus temperature from these studies are shown in **Figure 5.10a**. The obtained in-plane thermal conductivity values of suspended SLG generally fall in the range of ~ 2000 – 4000 W/m/K at room temperature, and decrease with increasing temperature, reaching about 700 – 1500 W/m/K at 500 K. The variation of obtained values could be attributed to different choices of graphene optical absorbance (in the analysis of the Raman data), thermal contact resistance, different sample geometries, sizes and qualities.

For comparison, we also plot the experimental thermal conductivity of diamond (Ho et al., 1972), graphite (Ho et al., 1972) and carbon nanotubes (CNTs) (Kim et al., 2001, Pop et al., 2006a) in **Figure 5.10a**. It is clear that suspended graphene has thermal conductivity as high as these carbon allotropes near room temperature, even higher than its three-dimensional counterpart, graphite, whose in-plane thermal conductivity in highly oriented pyrolytic

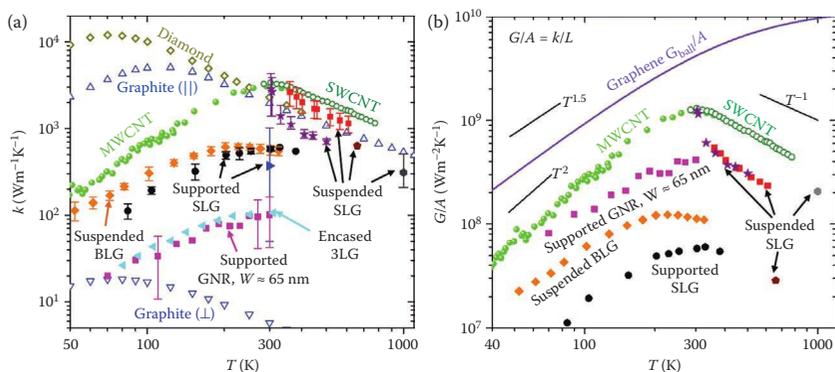


FIGURE 5.10 (a) Experimental thermal conductivity k as a function of temperature T : representative data for suspended CVD SLG by Chen et al. (2011) (solid red squares), suspended exfoliated SLG by Lee et al. (2011) (solid purple asterisk) and Faugeras et al. (2010) (solid brown pentagon), suspended SLG by Dorgan et al. (2013) (solid grey hexagon), suspended exfoliated BLG by Pettes et al. (2011) (solid orange diamond), supported exfoliated SLG by Seol et al. (2010) (solid black circle), supported CVD SLG by Cai et al. (2010) (solid blue right-triangle), encased exfoliated 3LG by Jang et al. (2010) (solid cyan left-triangle), supported exfoliated GNR of $W \approx 65$ nm by Bae et al. (2013) (solid magenta square), type IIa diamond (Ho et al., 1972) (open gold diamond), graphite in-plane (Ho et al., 1972) (open blue up-triangle), graphite cross-plane (open blue down-triangle), suspended SWCNT by Pop et al. (2006a) (open dark-green circle) and multi-walled CNT by Kim et al. (2001) (solid light-green circle). (b) Thermal conductance per cross-sectional area, $G/A = k/L$, converted from thermal conductivity data in (a), compared with the theoretical ballistic limit of graphene (solid line) (Bae et al., 2013). Data in (a) whose sample L is unknown or not applicable are not shown in (b). (Xu, Y., Li, Z. and Duan, W.: Thermal and thermoelectric properties of graphene. *Small*. 2014. 10. 2182–2199. Copyright Wiley-VCH Verlag GmbH & Co. KGaA. Reproduced with permission.)

graphite is ~ 2000 W/m/K at 300 K. The currently available data of graphene based on the Raman thermometry technique only cover the temperature range of ~ 300 – 600 K, except one at ~ 660 K reported by Faugeras et al. (2010) showing $k \approx 630$ W/m/K. For higher temperature, Dorgan et al. (2013) used the electrical breakdown method for thermal conductivity measurements and found $k \approx 310$ W/m/K at 1000 K for suspended SLG. The overall trend of the current graphene data from 300 to 1000 K shows a steeper temperature dependence than graphite (see **Figure 5.10a**), consistent with the extrapolation of thermal conductivity by Dorgan et al. (2013). This behaviour could be attributed to stronger second-order three-phonon scattering (relaxation time $\tau \sim T^{-2}$) in graphene than graphite enabled by the flexural (ZA) phonons of suspended graphene (Nika et al., 2012), similar to the observations in single-walled CNTs (SWCNTs) (Mingo and Broido, 2005, Pop et al., 2006a). For temperature below 300 K, the micro-resistance thermometry technique

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(Sadeghi et al., 2012, Xu et al., 2014b) needs to be employed. Xu et al. (2014a) performed such measurements for suspended SLG, and for a 7- μm -long sample, they obtained $k \sim 1500 - 1800 \text{ W/m/K}$ at 300 K and $\sim 500 - 600 \text{ W/m/K}$ at 120 K, the range arising from different estimations of thermal contact resistance.

It is instructive to compare experimental results with the theoretical ballistic phonon transport limit of graphene, so we convert reported k in **Figure 5.10a** to thermal conductance per unit cross-sectional area, $G/A = k/L$ in **Figure 5.10b**, comparing them with the ballistic limit, G_{ball}/A . The ballistic limit can be theoretically calculated based on the full phonon dispersion (Serov et al., 2013) and analytically approximated as

$$\frac{G_{\text{ball}}}{A} \approx \left[\frac{1}{4.4 \times 10^5 T^{1.68}} + \frac{1}{1.2 \times 10^{10}} \right]^{-1}, \quad (5.8)$$

over the temperature range 1–1000 K (Bae et al., 2013). Above room temperature, measured G/A of suspended, few-micron long SLG is over one order of magnitude lower than G_{ball}/A , indicating the diffusive transport regime. The value of Faugeras et al. (2010) is much lower than others because of a much larger $L = 22 \mu\text{m}$ (radius) of their suspended graphene. More importantly, graphene phonon mean free path (MFP), λ can be estimated based on G_{ball}/A and diffusive thermal conductivity (k_{diff}), that is, $\lambda = (2/\pi)k_{\text{diff}}/(G_{\text{ball}}/A)$ (Pop et al., 2012, Bae et al., 2013; Xu et al., 2014b). Since most k values measured on few-micron graphene samples can be approximated as k_{diff} , the estimated phonon MFP is $\sim 300 - 600 \text{ nm}$ for suspended SLG at room temperature.

5.3.2 Extrinsic Thermal Conductivity of Graphene

The long phonon MFP in pristine graphene would suggest that it is possible to tune thermal conductivity more effectively by introducing extrinsic scattering mechanisms which dominate over intrinsic scattering mechanisms in graphene. For example, isotope scattering, normally unimportant with respect to other scattering processes, could become significant in graphene thermal conduction. In the following, we discuss various scattering mechanisms and their influences on thermal conduction in graphene.

5.3.2.1 Isotope Effects

The knowledge of isotope effects on thermal transport properties is valuable for tuning heat conduction in graphene. Natural abundance carbon materials are made up of two stable isotopes of ^{12}C (98.9%) and ^{13}C (1.1%). Changing isotope composition can modify the dynamic properties of crystal lattices and affect their thermal conductivity (Hu et al., 2010, Lindsay et al., 2013). For instance, at room temperature, isotopically purified diamond has a thermal conductivity of $\sim 3300 \text{ W/m/K}$ (Anthony et al., 1990, Berman, 1992), about 50% higher than that of natural diamond, $\sim 2200 \text{ W/m/K}$ (Ho et al., 1972). Similar effects have also been observed in one-dimensional nanostructures, boron nitride nanotubes (Chang et al., 2006). Very recently, the first experimental

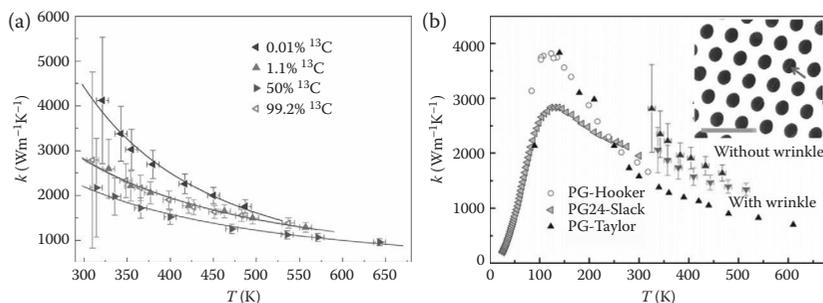


FIGURE 5.11 (a) Thermal conductivity of suspended CVD graphene as a function of temperature for different ^{13}C concentrations, showing isotope effect. (Reprinted by permission from Macmillan Publishers Ltd. *Nat. Mater.*, Chen, S. S. et al., 11, 203–207, copyright 2012.) (b) Thermal conductivity of suspended CVD graphene with (down-triangle) and without (up-triangle) wrinkles as a function of temperature. Also shown in comparison are the literature thermal conductivity data of pyrolytic graphite samples (Slack, 1962, Hooker et al., 1965, Taylor, 1966). Inset shows the SEM image of CVD graphene on the Au-coated SiN_x holey membrane. The arrow indicates a wrinkle. Scale bar is $10\ \mu\text{m}$. (Adapted from Chen, S. S. et al., Thermal conductivity measurements of suspended graphene with and without wrinkles by micro-Raman mapping, *Nanotechnology*, 23, 365701, Copyright 2012, Institute of Physics.)

work to show the isotope effect on graphene thermal conduction was reported by Chen et al. (2012b), who synthesized CVD graphene with various percentages of ^{13}C . Their graphene flakes were suspended over $2.8\text{-}\mu\text{m}$ -diameter holes and thermal conductivity was measured by the Raman thermometry technique. As shown in **Figure 5.11a**, compared with natural abundance graphene (1.1% ^{13}C), the k values were enhanced in isotopically purified samples (0.01% ^{13}C), and reduced in isotopically mixed ones (50% ^{13}C).

5.3.2.2 Structural Defect Effects

Structural defects are common in fabricated graphene, especially in CVD grown graphene (Wood et al., 2011, Koepke et al., 2013). The effects of wrinkles (Chen et al., 2012a) and grain size (Vlassiuk et al., 2011) on the thermal conduction of suspended single-layer CVD graphene have been examined in experiments by using the Raman thermometry technique. Chen et al. (2012a) found that the thermal conductivity of graphene with obvious wrinkles (indicated by arrows in the inset of **Figure 5.11b**) is about 15%–30% lower than that of wrinkle-free graphene over their measured temperature range, $\sim 330\text{--}520\ \text{K}$ (**Figure 5.11b**). Vlassiuk et al. (2011) measured suspended graphene with different grain sizes obtained by changing the temperature of CVD growth. The grain sizes were estimated to be $\ell_G = 150\ \text{nm}$, $38\ \text{nm}$ and $1.3\ \text{nm}$ in different samples in terms of the intensity ratio of the G peak to D peak in Raman spectra (Cançado et al., 2006). Since grain boundaries in graphene serve as extended defects and scatter phonons, graphene with smaller grain sizes are expected to

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suffer more frequent phonon scattering. Their measured thermal conductivity shows the expected decrease for smaller grain sizes, indicating the grain boundary effect on thermal conduction. The dependence on the grain size shows a weak power law, $k \sim \ell_G^{1/3}$, for which there is no theoretical explanation yet (Vlassioux et al., 2011). However, for SiO₂-supported graphene, recent theoretical work based on the NEGF method showed a similar but stronger dependence of k on the grain size ℓ_G in the range of $\ell_G < 1 \mu\text{m}$ (Serov et al., 2013). Further experimental studies are required to reveal the grain size effects on the thermal transport of both suspended and supported graphene.

5.3.2.3 Substrate Effects in Supported Graphene

For practical applications, graphene is usually in contact with a substrate in electronic and optoelectronic devices, so it is important to understand substrate effects on the thermal properties of supported graphene (Ong and Pop, 2011, Guo et al., 2012, Xu and Buehler, 2012, Chen et al., 2013). Seol et al. (2010, 2011) measured exfoliated SLG on a 300-nm-thick SiO₂ membrane by using the micro-resistance thermometry technique. The observed thermal conductivity is $k \sim 600 \text{ W/m/K}$ near room temperature (solid black circles in **Figure 5.10a**). This value is much lower than those reported for freely suspended SLG via the Raman thermometry technique, but is still relatively high compared with those of bulk silicon ($\sim 150 \text{ W/m/K}$) and copper ($\sim 400 \text{ W/m/K}$). Another study by Cai et al. (2010) showed CVD SLG supported on Au also has a decreased thermal conductivity, $\sim 370 \text{ W/m/K}$, and this lower value could be caused by grain boundary scattering (Serov et al., 2013). If using 600 W/m/K as k_{diff} , phonon MFP for SiO₂-supported graphene is estimated to be $\sim 90 \text{ nm}$ at room temperature (Pop et al., 2012, Bae et al., 2013, Xu et al., 2014b). The thermal conductivity reduction in supported graphene is attributed to substrate scattering, which strongly affects the out-of-plane flexural (ZA) mode of graphene (Seol et al., 2010, Ong and Pop, 2011, Qiu and Ruan, 2012). This effect becomes stronger in encased graphene, where graphene is sandwiched between bottom and top SiO₂. Jang et al. (2010) measured such SiO₂-encased graphene samples using the micro-resistance thermometry technique. The obtained k for encased SLG is reported to be below 160 W/m/K , and that for encased three-layer graphene (3LG) is shown as cyan triangles in **Figure 5.10a**. For encased graphene, besides the phonon scattering by bottom and top oxides, the deposition of the top SiO₂ layer could cause defects in graphene, which can further lower thermal conductivity. Knowing the thermal conductivity of supported and encased graphene is useful for analysing heat dissipation in graphene transistors and interconnects.

5.3.2.4 Size Effects and Boundary Scattering

In macroscopic bulk materials, thermal conductance satisfies Fourier's scaling law in the diffusive region, $G = kA/L$, where the thermal conductivity k is an intrinsic material property, independent of system size. This scaling law can break down in nanostructures through two mechanisms: (i) non-diffusive (quasi-ballistic) thermal transport and (ii) boundary effects become important. For non-diffusive transport, k becomes length dependent. It is proportional to

L as $k_{\text{ball}} = (G_{\text{ball}}/A)L$ in the ballistic limit, gets saturated in the diffusive limit, and typically grows gradually with increasing L in the intermediate region. In nanostructures, boundary effects cannot be neglected, and k becomes dependent on lateral sizes due to boundary scattering. The relatively long intrinsic phonon MFP of graphene (100–600 nm) makes the observations of such size effects on thermal transport possible.

The length-dependent k has been reported by Bae et al. (2013) and Xu et al. (2014a) in SiO₂-supported and suspended SLG, respectively. The measured k is reduced as the transport length decreases over a wide temperature range (see **Figure 5.12a**), and both studies show that the thermal transport enters the quasi-ballistic regime when L is a few hundred nanometres, comparable to phonon MFP of graphene. The observed L -dependent k can be captured by a simple ballistic-diffusive model (Pop et al., 2012, Bae et al., 2013, Xu et al., 2014b)

$$k(L) = \left[\frac{1}{(G_{\text{ball}}/A)L} + \frac{1}{k_{\text{diff}}} \right]^{-1}, \tag{5.9}$$

with theoretically calculated G_{ball}/A and properly fitted k_{diff} (see solid lines in **Figure 5.12a**).

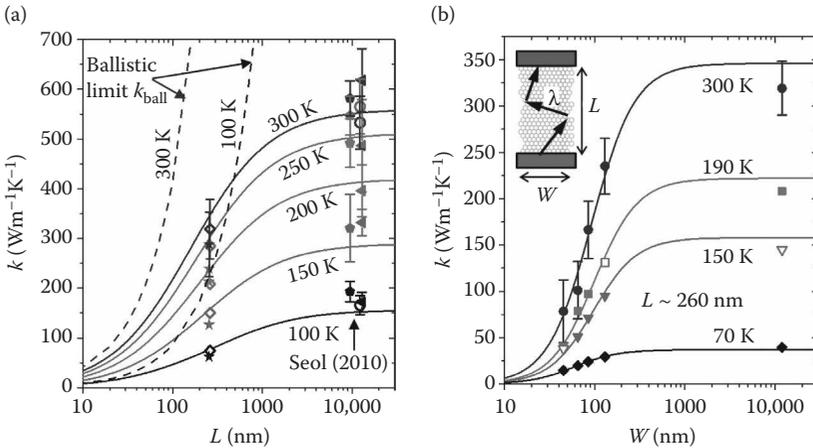


FIGURE 5.12 (a) Thermal conductivity reduction with length for ‘wide’ graphene samples ($W \gg \lambda$), compared to the ballistic limit ($k_{\text{ball}} = G_{\text{ball}}L/A$) at several temperatures. Symbols are data for ‘short’ (Bae et al., 2013) and ‘long’ (Seol et al., 2010) samples. Solid lines are model from **Equation 5.9**. (b) Thermal conductivity reduction with width for GNRs, all with $L \approx 260$ nm. Symbols are experimental data (Bae et al., 2013) and lines are fitted model. Inset shows a schematic of edge scattering in GNRs with dimensions comparable to the MFP λ . (Reprinted by permission from Macmillan Publishers Ltd. *Nat. Commun.*, Bae, M.-H. et al., Ballistic to diffusive crossover of heat flow in graphene ribbons, 4, 1734, copyright 2013.)

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The lateral size effects, that is, width-dependence of graphene thermal transport has also been measured by Bae et al. (2013) on GNRs with $W \sim 45\text{--}130$ nm, implemented by developing a substrate-supported thermometry platform (Li et al., 2014). The significant decrease of k is observed when $W < 200$ nm (see **Figure 5.12b**), due to increased edge scattering in narrower GNRs (see inset of **Figure 5.12b**). Through electrical breakdown measurements, Liao et al. (2011) were able to estimate k of CNT-unzipped GNRs (Jiao et al., 2009). Although the obtained values are slightly higher than those of Bae et al. (2013) for similar widths, considering that CNT-unzipped GNRs have smoother edges (Jiao et al., 2009, Kosynkin et al., 2009) (less edge roughness scattering), the two studies are essentially consistent.

5.3.2.5 Interlayer Effects in Few-Layer Graphene

Interlayer scattering as well as top and bottom boundary scattering could take place in few-layer graphene (FLG), which could be another mechanism to modulate graphene thermal conductivity. It is interesting to investigate the evolution of the thermal conductivity of FLG with increasing thickness, denoted by the number of atomic layers (N), and the critical thickness needed to recover the thermal conductivity of graphite.

Several experimental studies on this topic have been conducted for encased (Jang et al., 2010), supported (Sadeghi et al., 2013) and suspended FLG (Ghosh et al., 2010, Jang et al., 2013), and their results are summarised in **Figure 5.13**. Jang et al. (2010) measured the thermal transport of SiO₂-encased FLG by using the substrate-supported, micro-resistance thermometry platform. They found that the room-temperature thermal conductivity increases from ~ 50 to ~ 1000 W/m/K as the FLG thickness increases from 2 to 21 layers, showing a trend to recover natural graphite k . This strong thickness dependence was explained by the top and bottom boundary scattering and disorder penetration into FLG induced by the evaporated top oxide (Jang et al., 2010). More recently, another similar yet less pronounced trend was observed in SiO₂-supported FLG by Sadeghi et al. (2013) using the suspended micro-resistance thermometry platform. As shown by filled circles in **Figure 5.13**, the measured room-temperature k increases slowly with increasing thickness, and the recovery to natural graphite would occur after more than 34 layers. The difference between the results by Jang et al. (2010) and Sadeghi et al. (2013) is not unexpected, because encased FLG k could be suppressed much more in thin layers than thick ones due to the effect of the top oxide, hence showing a stronger thickness dependence.

For suspended FLG, there are two contradictory observations in the thickness dependence. At first, based on the Raman thermometry technique, Ghosh et al. (2010) showed a decrease of suspended FLG k from the SLG high value to regular graphite value as thickness increases from 2 to 8 layers (open diamonds in **Figure 5.13**). The k reduction was explained by the interlayer coupling and increased phase-space states available for phonon Umklapp scattering in thicker FLG (Ghosh et al., 2010). However, a very recent study (Jang et al., 2013) seems to show a different thickness trend for suspended FLG. They measured thermal conductivity of suspended graphene of 2–4 and 8 layers by using a

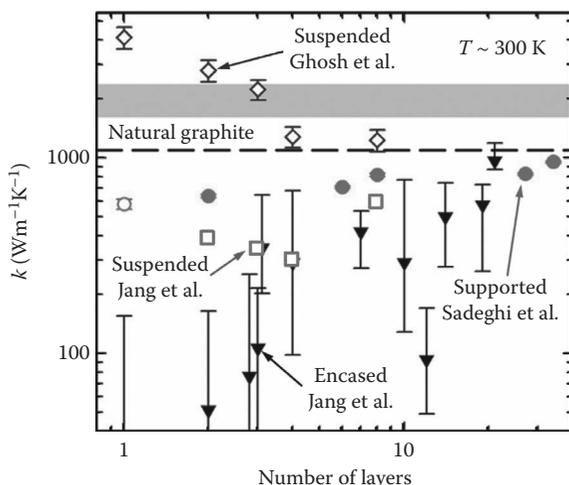


FIGURE 5.13 Experimental in-plane thermal conductivity near room temperature as a function of the number of layers N for suspended graphene by Ghosh et al. (2010) (open diamond) and Jang et al. (2013) (open square), SiO_2 -supported graphene by Seol et al. (2010) (open circle) and Sadeghi et al. (2013) (solid circle) and SiO_2 -encased graphene by Jang et al. (2010) (solid black triangle). The data show a trend to recover the value (dashed line) measured by Sadeghi et al. (2013) for natural graphite source used to exfoliate graphene. The grey-shaded area shows the highest reported k values of pyrolytic graphite (Slack, 1962, Hooker et al., 1965, Taylor, 1966). (Sadeghi, M. M., Jo, I. and Shi, L. Phonon-interface scattering in multilayer graphene on an amorphous support. *Proc. Natl. Acad. Sci. USA*, 110, 16321–16326, Copyright 2013 National Academy of Sciences, U.S.A.)

modified T-bridge micro-resistance thermometry technique. The obtained room-temperature k for 2–4 layers is about 300–400 W/m/K with no apparent thickness dependence, whereas k for 8-layer shows an increase to ~ 600 W/m/K (open squares in **Figure 5.13**). Surprisingly, this trend is qualitatively in agreement with that of Sadeghi et al. (2013) for *supported* FLG; both show similar increasing amounts of k from 2 to 8 layers (**Figure 5.13**), despite a small decrease from 2 to 4 layers in the former, which could arise from different sample qualities and measurement uncertainty. Given the opposite thickness trends of Ghosh et al. (2010) and Jang et al. (2013), further experiments are required to clarify the real thickness-dependent k in *suspended* FLG.

5.3.2.6 Cross-Plane Thermal Conduction

A remarkable feature of graphite and graphene is that their thermal properties are highly anisotropic. Despite high thermal conductivity along the in-plane direction, heat flow along the cross-plane direction (c -axis) is hundreds of times weaker, limited by weak van der Waals interactions between layers (for graphite) or with adjacent materials (for graphene). For example, the

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thermal conductivity along the c -axis of pyrolytic graphite is only ~ 6 W/m/K at room temperature (Ho et al., 1972) (Figure 5.10a). For graphene, as it is often attached to a substrate or embedded in a medium, heat conduction in the cross-plane direction is characterised by the thermal interface resistance (or conductance, G_{\perp}) with adjacent materials, which could become a limiting dissipation bottleneck in highly scaled graphene devices and interconnects (Bae et al., 2010, 2011, Behnam et al., 2012, Pop et al., 2012, Islam et al., 2013).

The thermal interface conductance G_{\perp} between graphene (or thin graphite) and other materials has been measured using the 3ω method (Chen et al., 2009b), the time-domain thermoreflectance technique (Koh et al., 2010, Mak et al., 2010, Schmidt et al., 2010; Hopkins et al., 2012, Norris et al., 2012, Zhang et al., 2013) and Raman-based method (Cai et al., 2010, Ermakov et al., 2013). Most experimental data available to date are shown in Figure 5.14, and they are consistent with each other in general, given the variations of sample quality and measurement techniques. Chen et al. (2009b) and Mak et al. (2010) showed the thermal interface conductance of the graphene/SiO₂ interface is

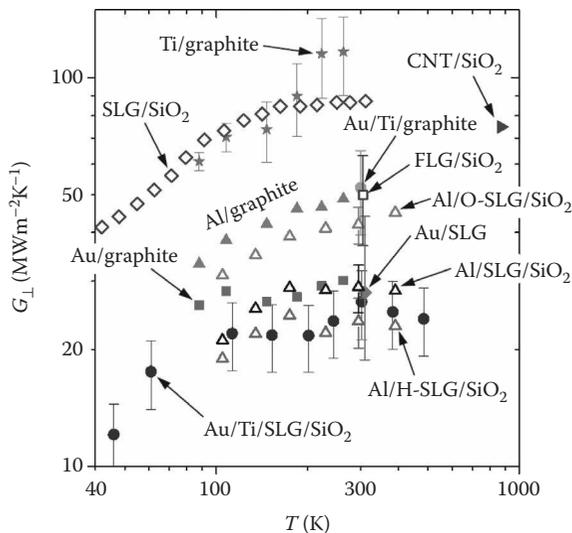


FIGURE 5.14 Experimental thermal interface conductance G_{\perp} versus temperature for SLG/SiO₂ by Chen et al. (2009b) (open diamond), FLG/SiO₂ by Mak et al. (2010) (open square), CNT/SiO₂ by Pop et al. (2007) (solid right-triangle), Au/SLG by Cai et al. (2010) (solid diamond), Au/Ti/SLG/SiO₂ (solid circle) and Au/Ti/graphite (solid circle) by Koh et al. (2010), interfaces of graphite with Au (solid square), Al (solid up-triangle), Ti (solid asterisk) by Schmidt et al. (2010), interfaces of Al/SLG/SiO₂ without treatment (Al/O-SLG/SiO₂, open black up-triangle), with oxygen treatment (Al/H-SLG/SiO₂, open up-triangle), and with hydrogen treatment (Al/H-SLG/SiO₂, open up-triangle) by Hopkins et al. (2012). (Xu, Y., Li, Z. and Duan, W.: Thermal and thermoelectric properties of graphene. *Small*, 2014, 10, 2182–2199. Copyright Wiley-VCH Verlag GmbH & Co. KGaA. Reproduced with permission.)

$G_{\perp} \sim 50\text{--}100 \text{ MW/m}^2/\text{K}$ at room temperature, with no strong dependence on the FLG thickness. Their values are close to that of CNT/SiO₂ (Pop et al., 2007), reflecting the similarity between graphene and CNT. Schmidt et al. (2010) measured G_{\perp} of graphite–metal interfaces, including Au, Cr, Al and Ti. Among them, the graphite–Ti interface has the highest $G_{\perp} \sim 120 \text{ MW/m}^2/\text{K}$ and the graphite–Au interface has the lowest $G_{\perp} \sim 30 \text{ MW/m}^2/\text{K}$ near room temperature. The G_{\perp} of graphite–Au is consistent with the value by Norris et al. (2012) and values of SLG–Au by Cai et al. (2010) and FLG/Au by Ermakov et al. (2013). Koh et al. (2010) later measured heat flow across the Au/Ti/*N*-LG/SiO₂ interfaces with the layer number $N = 1 - 10$. Their observed room-temperature G_{\perp} was $\sim 25 \text{ MW/m}^2/\text{K}$, which shows a very weak dependence on the layer number N and is equivalent to the total thermal conductance of Au–Ti–graphite and graphene–SiO₂ interfaces acting in series. This indicates that the thermal resistance of two interfaces between graphene and its environment dominates over that between graphene layers. Interestingly, Hopkins et al. (2012) showed the thermal conduction across the Al–SLG–SiO₂ interface could be manipulated by introducing chemical adsorbates between the Al and SLG. As shown in **Figure 5.14**, their measured G_{\perp} of untreated Al/SLG/SiO₂ is $\sim 30 \text{ MW/m}^2/\text{K}$ at room temperature, in agreement with Zhang et al. (2013). The G_{\perp} increases to $\sim 42 \text{ MW/m}^2/\text{K}$ for oxygen-functionalised graphene (O-SLG), and decreases to $\sim 23 \text{ MW/m}^2/\text{K}$ for hydrogen-functionalised graphene (H-SLG). These effects were attributed to changes in chemical bonding between the metal and graphene, and are consistent with the observed enhancement in G_{\perp} from the Al/diamond (Stoner et al., 1992) to Al/O-diamond interfaces (Collins et al., 2010).

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